ULg 4.1

## Chapter 4: Theoretical basis of LOTOS

## • Translation of LOTOS behaviour expressions into a mathematical model

- The Labelled Transition System (LTS) model
- Operational semantic rules
- Concept of an equivalence (bisimulation) over LOTOS processes

## • Algebraic data type

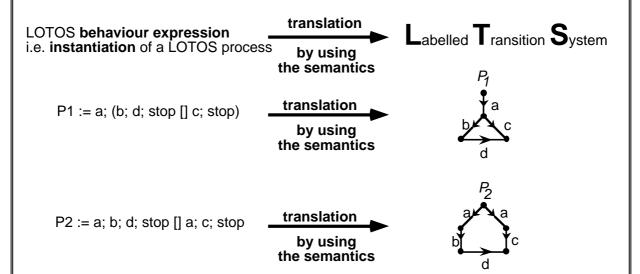
- Equational theory, congruence of terms
- Operational semantics of (full) LOTOS

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### Translation into a LTS model

The LOTOS **operational** semantics is defined by axioms and inference rules for **all** LOTOS operators.



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### Labelled Transition System

A Labelled Transition System Sys is a 4-tuple <S, A, T, so > where

- (i) S is a non-empty set of **states**,
- (ii) A is a set of actions,
- (iii) T is a set of **transition relations**  $Ta \subseteq S \times S$ , one for each  $a \in A$ ;

Ta is a set of **transitions** of the form: cur  $\xrightarrow{a}$  next, where cur, next  $\in$  S

(iv)  $s_0 \in S$  is the **initial state** of Sys.

A state is unambiguously identified by a behaviour expression

An **action** is of the form  $\mathbf{g}\mathbf{v}_1...\mathbf{v}_n$  where g is a gate name and the  $v_i$  are values of some sort

We define: name  $(gv_1...v_n) = g$ 

There is a distinguished (internal) action: i, which has no associated value.

There is a distinguished (terminating) gate name:  $\delta$ 

But we will consider first Basic LOTOS (without data types)

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# Operational semantic rules for Basic LOTOS

$$a; P \xrightarrow{a} P$$

$$\frac{P \stackrel{a}{\rightarrow} P'}{P [] Q \stackrel{a}{\rightarrow} P'}$$

$$\frac{P \xrightarrow{a} P'}{P ||\Gamma|| Q \xrightarrow{a} P' ||\Gamma|| Q} (a \notin \Gamma \cup \{\delta\})$$

$$a; P \xrightarrow{a} P \qquad exit \xrightarrow{\delta} stop \qquad \frac{P \xrightarrow{a} P'}{P [] Q \xrightarrow{a} P'}$$

$$\frac{P \xrightarrow{a} P'}{P |[\Gamma]| Q \xrightarrow{a} P' |[\Gamma]| Q} (a \notin \Gamma \cup \{\delta\}) \qquad \frac{P \xrightarrow{a} P', Q \xrightarrow{a} Q'}{P |[\Gamma]| Q \xrightarrow{a} P' |[\Gamma]| Q'} (a \in \Gamma \cup \{\delta\})$$

$$\frac{P \xrightarrow{a} P'}{\text{hide } \Gamma \text{ in } P \xrightarrow{a} \text{ hide } \Gamma \text{ in } P'} (a \notin \Gamma) \qquad \frac{P \xrightarrow{a} P'}{\text{hide } \Gamma \text{ in } P \xrightarrow{i} \text{ hide } \Gamma \text{ in } P'} (a \in \Gamma)$$

$$\frac{P \xrightarrow{a} P'}{\text{hide } \Gamma \text{ in } P \xrightarrow{a} \text{hide } \Gamma \text{ in } P'} (a \notin \Gamma)$$

$$\frac{P \xrightarrow{a} P'}{\text{hide } \Gamma \text{ in } P \xrightarrow{i} \text{hide } \Gamma \text{ in } P'} (a \in \Gamma)$$

$$\frac{P \stackrel{a}{\rightarrow} P'}{P >> Q \stackrel{a}{\rightarrow} P' >> Q} (a \neq \delta) \qquad \frac{P \stackrel{\delta}{\rightarrow} P'}{P >> Q \stackrel{\dot{i}}{\rightarrow} Q}$$

$$\frac{P \stackrel{a}{\rightarrow} P'}{P [> Q \stackrel{a}{\rightarrow} P' [> Q} (a \neq \delta) \qquad \frac{P \stackrel{\delta}{\rightarrow} P'}{P [> Q \stackrel{\delta}{\rightarrow} P'} \qquad \frac{Q \stackrel{a}{\rightarrow} Q'}{P [> Q \stackrel{a}{\rightarrow} Q']}$$

$$\frac{P \xrightarrow{\delta} P'}{P >> Q \xrightarrow{\dot{I}} Q}$$

$$\frac{P \xrightarrow{a} P'}{P > Q \xrightarrow{a} P' > Q} (a \neq \delta)$$

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$$\frac{P \xrightarrow{\delta} P'}{P [> Q \xrightarrow{\delta} P']}$$

$$\frac{Q \stackrel{a}{\rightarrow} Q'}{P [> Q \stackrel{a}{\rightarrow} Q']}$$

$$\frac{P[g_1/h_1,...g_n/h_n] \xrightarrow{a} P', Q[h_1,...h_n] := P}{Q[g_1, ...g_n] \xrightarrow{a} P'}$$

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### Derivation of the LTS associated with a (closed) LOTOS behaviour expression

The given system of axioms and inference rules (denoted D) is used to build a LTS <S, A, T, so> associated with any **closed** behaviour expression B as follows:

s<sub>0</sub> = B No free variables

S = Der (B) where Der (B) is the set of derivatives of B,

i.e. the smallest set satisfying

- (a)  $B \in Der(B)$
- (b) if B'  $\in$  Der (B) and D  $\mid$  B'  $\stackrel{a}{\Rightarrow}$  B" for some a, then B"  $\in$  Der (B).

Intuitively, S is the set of states reachable from the initial state B.

 $A = G \cup \{i, \delta\}$  where G is the set of gates of B,

A is the alphabet of the transition system, i.e. all the possible actions.

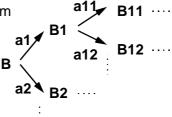
$$T = \{ A \mid a \in A \}$$
 where  $A = \{ A \mid B_2 > B_1 \mid B_2 > B_2 \}$ 

T is the set of transitions derived from D.

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## **Derivation tree**

A derivation tree (of B) is of the form



where the outgoing arcs from each non-leaf node are all the actions of the expression at that node.

The tree can be infinite in depth and in width (e.g. in presence of recursion). It can be seen as the unfolding of the LTS associated with B.

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#### **Equivalence over processes**

We seek an appropriate equivalence relation over processes, which gives no special status to the silent i-action.

There are of course other weaker equivalences which reflect the idea that the i-action should indeed be silent, i.e. unobservable.

Perhaps the most obvious equivalence of processes is one which requires merely that they should possess the same traces (or sequences of transitions). More exactly, we might declare P and Q to be equivalent just when, for all trace  $\sigma$  = a1.a2...an  $\in$  A\*,

$$P \xrightarrow{\sigma} iff Q \xrightarrow{\sigma}$$
.

But consideration of deadlock leads to the rejection of this proposal. For P and Q would be equivalent if they have the following derivation trees:

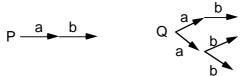


But in this case, after performing a, P will always be able to perform b while Q may not. Thus, in an "environment" which *demands* b after a, P will not deadlock while Q may. So, apparently this equivalence is too large.

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## **Equivalence over processes (2)**

On the other hand we may be too restrictive; we may take P and Q to be equivalent just when their derivation trees are isomorphic. This would deny the equivalence of P and Q with trees like



even though, at each stage, the same actions are possible.

## We therefore seek an intermediate notion, with the following property:

P and Q are equivalent iff

for all  $a \in A$ , **each** a-successor of P is equivalent to **some** a-successor of Q, and conversely

where an a-successor of P is any P' such that P  $\stackrel{a}{\rightarrow}$  P'

Such an equivalence (denoted ~) exists, is a congruence, and has useful algebraic properties.

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### Towards a definition of ~

This **property** can be expressed more formally as follows:

 $P \sim Q$  iff, for all  $a \in A$ ,

(\*)

- (i) whenever  $P \xrightarrow{a} P'$  then  $\exists Q' \bullet Q \xrightarrow{a} Q'$  and  $P' \sim Q'$ ;
- (ii) whenever  $Q \xrightarrow{a} Q'$  then  $\exists P' \bullet P \xrightarrow{a} P'$  and  $P' \sim Q'$

However, it is **not a definition**, since there are many relations ~ which satisfy it (including the empty relation).

What we really want is the largest (or weakest, or more generous) relation ~ which satisfies the above property (\*).

## But is there a largest such relation?

To see that there is, we adopt an approach which may seem indirect, but which gives us more than a positive answer to the question; it gives us a natural and powerful proof technique.

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### Strong bisimulation and strong equivalence

#### **Definition**

Let F be a function over binary relations  $R \subseteq S \times S$  defined as follows:

$$<$$
P, Q $>$   $\in$  F (R) iff, for all a  $\in$  A,

(i) whenever 
$$P \xrightarrow{a} P'$$
 then  $\exists Q' \bullet Q \xrightarrow{a} Q'$  and  $\langle P', Q' \rangle \in R$ ;

(ii) whenever Q 
$$\stackrel{a}{\rightarrow}$$
 Q' then  $\exists$  P'  $\bullet$  P  $\stackrel{a}{\rightarrow}$  P' and  $<$ P', Q'>  $\in$  R

Note that F is monotone, i.e.  $R1 \subseteq R2$  implies F (R1)  $\subseteq$  F (R2).

#### **Definition**

 $R \subseteq S \times S$  is a strong bisimulation iff  $R \subseteq F(R)$ 

The empty relation, the identity relation, and the union of two strong bisimulations are strong bisimulations

#### **Definition**

P and Q are strongly equivalent (or strongly bisimilar), written P ~ Q,

if **there exists** a strong bisimulation R such that  $\langle P, Q \rangle \in R$ .

This may be equivalently expressed as follows:  $\sim = \cup \{R \mid R \text{ is a strong bisimulation}\}$ 





An example of a strong bisimulation:

R is composed of all the pairs of states of the same colour



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### Properties of ~

1. ~ is the largest strong bisimulation

Because it is the union of all strong bisimulations, which is still a strong bisimulation

~ is an equivalence

Because it is reflexive, symmetric and transitive (The identity relation, the converse of a strong bisimulation and the composition of two strong bisimulations are strong bisimulations)

3.  $\sim$  is a fixed point of F, i.e.  $\sim$  = F ( $\sim$ )

We know that  $\sim \subseteq F(\sim)$  because  $\sim$  is a strong bisimulation. We show that  $F(\sim) \subseteq \sim$ . From  $\sim \subseteq F(\sim)$  and the monotonicity of F, we derive  $F(\sim) \subseteq F(F(\sim))$ . So  $F(\sim)$  is a strong bisimulation, and then  $F(\sim) \subseteq \sim$  because  $\sim$  is the largest one.

4. ~ is the largest fixed point of F

Let R be a fixed point. Then R is a strong bisimulation as any fixed point. Then R  $\subseteq$  ~ because ~ is the largest strong bisimulation. So ~ being a fixed point is the largest one.

So ~ can be defined as **the largest relation** ~ that satisfies the following property:

 $P \sim Q$  iff, for all  $a \in A$ , (i) whenever  $P \stackrel{a}{\rightarrow} P'$  then  $\exists Q' \bullet Q \stackrel{a}{\rightarrow} Q'$  and  $P' \sim Q'$ ;

© Guy Leduc Université de Liège : (ii) whenever  $Q \xrightarrow{a} Q'$  then  $\exists P' \bullet P \xrightarrow{a} P'$  and  $P' \sim Q'$ 

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## Simpler definition of a strong bisimulation

A relation  $R \subseteq S \times S$  is a strong bisimulation iff:

If  $\langle P, Q \rangle \in R$  then, for all  $a \in A$ ,

- (i) whenever  $P \xrightarrow{a} P'$  then  $\exists Q' \bullet Q \xrightarrow{a} Q'$  and  $\langle P', Q' \rangle \in R$ ;
- (ii) whenever Q  $\overset{a}{\rightarrow}$  Q' then  $\exists$  P'  $\bullet$  P  $\overset{a}{\rightarrow}$  P' and  $\lt$ P', Q'>  $\in$  R

Here F is not defined explicitly, and the inclusion  $R \subseteq F(R)$  is implicit in the if-then-else construct:

$$<$$
P, Q $>$   $\in$  R implies  $<$ P, Q $>$   $\in$  F (R),

and 
$$\langle P, Q \rangle \in F(R)$$
 iff, for all  $a \in A$ , (i) and (ii) hold.

This definition is the standard definition of the strong bisimulation.

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#### Proof technique for ~

#### **Problem**

Given two processes P and Q. Prove that P ~ Q.

## Method (= exhibit an appropriate strong bisimulation containing the pair <P, Q>)

Find a relation R such that  $\langle P, Q \rangle \in R$ . This is like finding an invariant.

Prove that R is a strong bisimulation.

#### **Example**

Prove that P [] P  $\sim$  P. Note that P is not defined explicitly! This is an open beh. expr.

Let 
$$R = Id \cup \{ \langle P [] P, P \rangle \mid P \in S \}$$
.

First case: let P [] P  $\xrightarrow{a}$  P'. It is enough to find P" such that P  $\xrightarrow{a}$  P" and <P', P">  $\in$  R.

But P [] P  $\xrightarrow{a}$  P' must be inferred from the choice rule, so P  $\xrightarrow{a}$  P' (premise of the rule).

Therefore, it suffices to take P'' = P' because  $Id \subseteq R$ .

The other cases are similar.

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#### Proof of the strong equivalence of two closed behaviour expressions

When the two behaviour expressions are **closed** and the associated LTS are **finite-state**, there are algorithms to prove the strong equivalence of the LTS in polynomial time (with respect to the size of the LTS, not the size of the LOTOS expression).

Example of a LOTOS expression that generates an infinite LTS:

B := a; stop ||| B

However, it is strongly equivalent to the LTS of a; B1 where B1 := a; B1 which is finite.

This is because (stop ||| (stop ||| P)) ~ (stop ||| P).

Therefore by using some strong equivalence laws, it is possible to extend the class of behaviour expressions that have associated finite LTS.

We will give some of them. Note that no sound and complete set of laws for ~ can exist because Basic LOTOS is Turing powerful.

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## Equational properties of ~

Monoid laws:

 $P [] Q \sim Q [] P \qquad \qquad P [] (Q [] R) \sim (P [] Q) [] R$ 

 $P [] P \sim P$   $P [] stop \sim P$ 

Note that the distributive law: a; (P [] Q) ~ a; P [] a; Q is **not** satisfied.

Static laws:

 $P | [\Gamma] | Q \sim Q | [\Gamma] | P$ 

 $P | [\Gamma] | (Q | [\Gamma] | R) \sim (P | [\Gamma] | Q) | [\Gamma] | R$  Note that the gate sets  $\Gamma$  must be equal

stop  $\Rightarrow$  P ~ stop exit  $\Rightarrow$  P ~ i; P

 $P >> (Q >> R) \sim (P >> Q) >> R$ 

Note that P >> stop ~ P and P ||| stop ~ P are **not** satisfied. Why?

 $P > (Q > R) \sim (P > Q) > R$   $P > stop \sim P$ 

 $(P [> Q) [] Q \sim P [> Q$  stop  $[> P \sim P]$ 

exit [> P ~ exit [] P

They can all be proved by exhibiting an appropriate strong bisimulation

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### **Expansion laws (or expansion theorems)**

The purpose of these laws is to expand behaviour expressions by pushing the parallel composition, the disabling and the hiding operators deeper in the process structure.

Let 
$$P = \Sigma$$
 {aj;  $Pj \mid j \in J$ } and  $Q = \Sigma$  {bk;  $Qk \mid k \in K$ } where  $\Sigma$  {Bj  $\mid j \in Nat$ } denotes B0 [] B1 [] B2 [] B3 [] ...

These expressions of P and Q can be seen as derivation trees.

### **Expansion laws:**

$$\begin{split} P \mid & [\Gamma] \mid Q \ \sim \ \Sigma \left\{ aj; \ (Pj \mid [\Gamma] \mid Q) \ \middle| \ j \in J, \ aj \not \in \Gamma \cup \left\{ \delta \right\} \right\} \\ & \left[ \left[ \right] \ \Sigma \left\{ bk; \ (P \mid [\Gamma] \mid Qk) \ \middle| \ k \in K, \ bk \not \in \Gamma \cup \left\{ \delta \right\} \right\} \right. \\ & \left[ \left[ \right] \ \Sigma \left\{ c; \ (Pj \mid [\Gamma] \mid Qk) \ \middle| \ j \in J, \ k \in K, \ c = aj = bk \in \Gamma \cup \left\{ \delta \right\} \right\} \\ & P \mid > Q \ \sim \ Q \ \left[ \left[ \right] \ \Sigma \left\{ aj; \ (Pj \mid > Q) \ \middle| \ j \in J, \ aj \neq \delta \right\} \ \left[ \left[ \right] \ \Sigma \left\{ aj; \ Pj \ \middle| \ j \in J, \ aj \in \Gamma \right\} \right. \\ & \text{hide } \Gamma \text{ in } P \ \sim \ \Sigma \left\{ aj; \ \text{hide } \Gamma \text{ in } Pj \ \middle| \ j \in J, \ aj \notin \Gamma \right\} \quad \left[ \left[ \right] \ \Sigma \left\{ i; \ \text{hide } \Gamma \text{ in } Pj \ \middle| \ j \in J, \ aj \in \Gamma \right\} \right. \end{split}$$

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### **Definition**

A LOTOS context C [•] is a LOTOS behaviour expression with a formal process parameter [•] called a hole.

Congruence

For example, C  $[\bullet]$  := hide a in  $(P \parallel \parallel \bullet)$  is a LOTOS context.

If C [•] is a context and P is a behaviour expression, then C [P] is the behaviour expression that is the result of replacing the • occurrence by P.

In the example above, C [Q] := hide a in (P ||| Q)

#### **Definition**

An equivalence relation R is a congruence in LOTOS iff, for all P, Q and LOTOS context C [•],  $\langle P, Q \rangle \in R$  implies  $\langle C[P], C[Q] \rangle \in R$ 

Theorem: ~ is a congruence in LOTOS

This allows the substitution of a process by a strongly equivalent one in any LOTOS context. **Note that the definition of a congruence is language dependent.** 

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#### Conclusion on ~

Strong equivalence (congruence) ~ provides a tractable notion of equality of processes. It allows many nontrivial equalities to be derived.

However, it is deficient in a vital respect: it treats the internal action i on the same basis as all other actions, and properties which we would expect to hold if i is unobservable, such as a; i; P = a; P, do not hold if '=' is taken to mean strong equivalence.

This defect can be removed by defining a weaker equivalence based on the concept of a weak bisimulation. Refer to chapter on equivalence relations.

However, as ~ is the strongest meaningful equivalence, all the equivalence laws that we have presented will remain valid when weaker equivalences are used in the sequel.

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## Algebraic data types

- Notion of algebraic data type
- ACT ONE semantics (equational theory, congruence of terms, quotient algebra, initial algebra)
- Operational semantics of (full) LOTOS
- (Free) constructor, semi-constructor, function
- Completeness and consistency

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### Algebraic data types

Data type: (It is not a set of values)

Characterized by one or more sets of values **AND** by the allowed operations on the values

#### Abstract data type:

Data are treated as abstract objects and the semantics of functions operating on data are described by properties

### Algebraic data type:

When properties are given in the form of axioms (logical formulas)

## Equational algebraic data type:

When the axioms are restricted to equations

### Positive conditional algebraic data type:

When the axioms are restricted to **implications from conjonctions of equations to one equation** (Horn Clause with equality)

E.g.: 
$$X = Z \& Z = Y \Rightarrow X = Y$$

ACT ONE is a positive conditional algebraic data type language.

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### Specification of an ADT in ACT ONE

An ADT in ACT ONE is specified by sorts, operations and (conditional) equations

I. Specification of sorts

sorts Nat

II. Specification of operations

```
opns 0: -> Nat
succ: Nat -> Nat
_+_: Nat, Nat-> Nat sorts + operations (over these sorts) = a signature
```

III. Specification of equations

```
eqns forall x, y : Nat ofsort Nat x + 0 = x ; x + succ(y) = succ(x+y) ;
```

Combining operations yields terms

= <u>representations</u> of values contained in the sorts.

E.g.: 0, succ(0), 0+0, 0+succ(0), succ(0+0)...

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### **Equational theory**

Let E be a set of equations over a set of terms.

The equational theory, Th (E), is the set of equations that can be obtained by taking

- all instances of equations in E as axioms, and
- reflexivity, symmetry, transitivity and context applications as inference rules.

For example, the following equations belong to the equational theory associated with the two equations given for \_+\_:

0 + 0 = 0 instance of first equation 0 + succ(0) = succ(0+0) instance of second equation

0 = 0 reflexivity

succ(0+0) = 0 + succ(0) symmetric of 0 + succ(0) = succ(0+0)

succ(0+0) = succ(0) by application of context succ(.) to 0 + 0 = 0

0 + succ(0) = succ(0) transitivity of 0 + succ(0) = succ(0+0) and succ(0+0) = succ(0)

In LOTOS, one uses the concept of **derivation system** instead of an equational theory. The derivation system associated with an ACT ONE specification is composed of the set of axioms and the set of inference rules enumerated in the definition of the equational theory.

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### Congruence and congruence class

Let <S,OP,E> be an ACT ONE specification (S = Sorts, OP = OPerations, E = Equations) and DS the derivation system generated from it.

Two ground terms s and t are called **E-congruent** iff DS  $\mid$ — s = t or simply E  $\mid$ — s = t

That is if  $s=t \in Th(E)$ 

Other notation: s 

t

The **E-congruence class** [t] of a ground term t is the set of all terms E-congruent to t.

Ground terms denote values. Congruent ground terms are different denotations for the same value. E.g. '2', '1'+'1', '0' + '2', ...

Each value will be represented by the **set** of all its denotations. This leads to the concept of a **quotient** term algebra.

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### Quotient term algebra or initial algebra

The **quotient term algebra** (or initial algebra) Q(E) of a set of equations E is a model in which the universe consists of one element for each E-congruence class of ground terms.

It is **initial** in the sense that the E-congruence classes are the smallest ones:

two terms are in the same class if this can be proved, otherwise they are considered distinct (no additional properties are considered)

Positive conditional algebraic data types constitute the **largest class** of algebraic data types for which **an initial algebra always exists**.

(e.g. a (non-positive conditional) axiom like a=b v b=c has no initial algebra)

The semantical interpretation of an ACT ONE specification <S,OP,E> is the many-sorted algebra <Dq, Oq>, called the **quotient term algebra**, where

- Dq is the set  $\{Q(s) \mid s \in S\}$  where  $Q(s) = \{[t] \mid t \text{ is a ground term of sort } s\}$  for each  $s \in S$
- Oq is the set of operations  $\{Q(op) \mid op \in OP\}$ , where the Q(op) are defined by

$$Q(op) ([t1], ... [tn]) = [op(t1, ... tn)]$$

The arguments and result of Q(op) are "classes of terms".

[0]	[succ(0)]	[succ(succ(0))]	
Q	(+)		

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#### **Derivations**

A **substitution**  $\sigma$  is a special kind of replacement operation, uniquely defined by a mapping from variables to terms.

Example: Let a substitution  $\sigma$  be defined by  $\{x \rightarrow succ(0), y \rightarrow 0\}$  and the term s = succ(x+y). Then  $s\sigma = succ(succ(0)+0)$ 

A **context** is a term with a hole. For example: succ(•).

 $s \leftrightarrow t$  iff  $s = u(l\sigma)$  and  $t = u(r\sigma)$  for some equation l=r, context  $u(\bullet)$  and substitution  $\sigma$ .

One term can be obtained from the other by one replacement of equal terms

For example:  $succ(0+0) \leftrightarrow succ(0)$  with equation x+0=x,  $\sigma=\{x\to 0\}$  and context  $succ(\bullet)$ 

 $s \overset{\star}{\leftrightarrow} t$  is the reflexive-transitive closure of  $s \overset{t}{\leftrightarrow} t$ There is a **derivation** between s and t

The following result holds:  $s \underset{E}{\leftrightarrow} t$  iff  $E \mid -- s = t$ 

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### Unification, matching and narrowing

Let E be a set of equations.

A substitution  $\sigma$  is an **E-unifier** of s = t if  $s\sigma = t$   $\sigma$ 

For example  $\sigma = \{x \to 0+0, y \to succ(0)\}\$  is a unifier of succ(x) = y (in the Nat theory)

s and t are **E-unifiable** if there exists an E-unifier of s = t

t **E-matches** s if there exists a substitution  $\sigma$  such that  $s\sigma = t$ 

The **unification problem** is to determine the set of all E-unifiers  $\sigma$  of s = t.

A narrower is an algorithm that finds E-unifiers

A **complete narrower** is an algorithm that solves the unification problem (i.e. that finds all the E-unifiers)

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#### **Operational semantics of full LOTOS**

### First phase: the flattening mapping

This phase produces a canonical LOTOS specification (CLS) where all identifiers are made **unique** (by a suitable relabelling) and **defined at one global level**.

A canonical LOTOS specification CLS is a 2-tuple <CAS, CBS> composed of:

- CBS = <PDEFS, pdef0> : a canonical behaviour specification, i.e. a set of process definitions PDEFS with an initial definition pdef0 ∈ PDEFS (the **behaviour** of the spec)
- CAS = <S,OP,E>: a canonical algebraic specification such that the signature <S, OP> contains all sorts and operations occurring in CBS

This flattening mapping is **partial** since only **static semantically** correct specifications have a well-defined CLS.

## Second phase: building of the derivation system DS of CAS

The semantic interpretation of CAS is the many-sorted Quotient term algebra Q(CAS)

#### Third phase: mapping of CLS onto a LTS

Based on a set of operational semantic rules (see next slide)

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## **Operational semantic rules for full LOTOS**

An  $\boldsymbol{action}$  is of the form  $\boldsymbol{gv_1...v_n}$  where g is a gate name and the  $v_i$  are values of some sort

We define: name  $(gv_1...v_n) = g$ 

Two examples of axioms:

Exit  $(E_1,...E_n) \xrightarrow{\delta V_1...V_n} stop$ 

provided that

vi = [Ei] if Ei is a ground term

 $\forall i \in Q (si)$  if Ei = any si

exit (true or false)  $\xrightarrow{\delta}$  true stop

 $gd_1 ...d_n$  [SP];  $P \xrightarrow{gv_1...v_n} [ty_1/y_1, ...ty_m/y_m] P$  provided that

vi = [Ei] if di = !Ei

 $vi \in Q$  (si) if di = ?xi:si

g?x:nat!true [x $\leq$ 1]; P  $\xrightarrow{g \ 1 \text{ true}}$   $\rightarrow$  [1/x] P

 ${y1,...ym} = {xi \mid di = ?xi:si }$ 

The tyj are term instances with [tyj] = vi if yj = xi and

DS |- [ty1/y1, ...tym/ym] SP

© Guy Leduc Université de Liège = This implies to find all the solutions of SP (Cf. unification problem)

#### **Constructors and functions**

There are algebraic data type languages in which the operations are clearly partitioned into two classes: the constructors and the functions.

Even if it is not the case in ACT ONE (where there are just operations), it is useful to make this distinction because most LOTOS tools are based on this distinction or require the user to provide this extra piece of information.

Constructors are used to 'build data'.

For example: 0 and succ to define the natural numbers

Functions are all the operations that are not constructors

For example: \_+\_

If there exists an equation that involves constructors **only**, these constructors are called **semi-constructors**.

This is because they are used to build data like constructors, but they also look like functions due to the presence of these equations.

Other constructors are called free constructors.

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```
Examples of semi-constructors
Integers
 sort int
 opns 0: -> int
                                      (* free constructor *)
          succ, pred: int -> int
                                     (* semi-constructors*)
 eqns forall x:int
          ofsort int
          succ(pred(x)) = x
          pred(succ(x)) = x
Sets
sort elem, set
                                        (* free constructors *)
(* free constructor *)
(* semi-constructor *)
opns a,b,c: -> elem
          Ø: -> set
          insert: elem,set -> set
eqns forall e1, e2: elem, s:set
          ofsort set
         insert (e1, insert (e1, s)) = insert (e1, s)
insert (e1, insert (e2, s)) = insert (e2, insert (e1, s))
                        Many tools don't like semi-constructors
```

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#### Removal of semi-constructors

**Example**: succ and pred are semi-constructors in the integer theory

ofsort int

succ (pred (x)) = x

pred (succ (x)) = x

These equations should be rewritten as follows:

succ(0) = succ'(0)

succ (succ'(x)) = succ'(succ'(x))

succ (pred'(x)) = x

pred(0) = pred'(0)

pred (pred'(x)) = pred'(pred'(x))

pred (succ' (x)) = x

succ' and pred' are **constructors** succ and pred are **functions** 



**pred'** (**succ'** (**x**)) ≠ **x** 

But terms like pred' (succ' (x)) should never appear

All terms composed of succ and pred can be rewritten into terms composed of either succ' only, or pred' only, but not both

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#### Completeness

The specification E is **sufficiently complete** (or "has no junk") **with respect to the set of constructors**, if every ground term t is provably equal to a constructor term (i.e. a term that is built from constructors only).

Informally, this means that all functions are total, or totally defined.

Partial functions lead to incompleteness and introduce "junk" terms.

Example of an incomplete specification:

```
sort nat
opns 0: -> nat
    succ: nat -> nat
    pred: nat -> nat
    ofsort nat
    pred (succ (x)) = x;
(* free constructor *)
(* free constructor *)
(* function *)

(* function *)
```

'pred (0)' cannot be proved equal to a constructor term. It is a "junk" term.

The reason is that the pred function is partial because no equation is given for 'pred (0)'.

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### Consistency

The specification E is **consistent** (or "has no confusion") **with respect to the set of constructors**, if for arbitrary ground **constructor** terms s and t,

$$E \mid -s = t$$
 iff  $E_C \mid -s = t$ 

where  $\mathbf{E}_{\mathbf{C}}$  is the subset of equations involving constructors only (e.g. pred(succ(int))=int)

Informally, a specification is consistent if constructor terms that cannot be equated by means of equations in  ${\sf E}_{\sf C}$  denote distinct values (i.e. no confusion).

If all constructors are free, then  $E_C = \emptyset$ , and s = t cannot hold for constructor terms s and t. Example of an inconsistent specification:

```
sort nat
```

```
opns 0: -> nat
    error: -> nat
    succ: nat -> nat
    pred: nat
```

One can prove 0 = error \* 0 = error but 0 = error cannot be proved from E

Guy Leduc In other words, the function \_\*\_ turns two distinct values into equivalent ones C

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